

EasyNAV EMG100

User Manual



CHCNAV

Version:

EMG V1.0.2





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1. Software Installation and Registration

1.1. Software Installation

The EasyNAV EMG100 software is designed specifically for EasyNAV tablet use and supports online upgrades.

➡ Return		System inf	ormation		
Remote Assistance				System information	
If you need help, click the Re 6-digit remote identification	emote Assista number to te	ance button below and chnical support.	d provide the Assistance	Tablet SN ICCID IMEI	unknown
OTA upgrade	OTA upgrade				
To update to the latest syste the upgrade is in progress.	To update to the latest system version or board version, click the respective upgrade button below. Do not power off while the upgrade is in progress.				
Current version: eMG1.0.2.	.20241204-Sir	mulate-Android			
Latest version: You are using the most up-to-date version					
Name M	Model	SN	Version	Status	
Stick Sensor IS	S300	19899656	NA/NA	Normal	😴 Upgrade

1.2. Software Login

This section provides detailed instructions for using the EasyNAV EMG100 software, helping you quickly become familiar with its operation.

Initial Setup:

- 1. Power on the tablet
- 2. Wait 3-5 seconds for the system disclaimer
- 3. Read the disclaimer carefully
- 4. Click "I have read and agree to the above statement" to proceed to login



Note:

- Use tourist mode for initial login
- Mobile phone login is not currently supported





1.3. Home Page Overview

The main interface of the EasyNAV EMG100 software shows the construction status map, parameter status bar, and shortcut keys.



Element	Name	Description	Action
1	Product Logo	Company Logo	View only
2	Elevation Difference	Distance between bucket tip and design surface	View only
3	Profile/Cross Section	Toggle between profile and cross section views	Click to switch
4	Bucket View	Dynamic bucket visualization	View only
5	View Switch	Toggle between the top and side views	Click to switch
6	Main Antenna Status	Displays satellite count and positioning quality	View only
7	Auxiliary Antenna Status	Shows heading positioning quality	View only
8	Main Antenna Differential Age	Base station signal delay	View only
9	Positioning Accuracy	Horizontal/Vertical accuracy values	View only



10	Network Signal	Current operator signal strength	View only
11	Wi-Fi Signal	Tablet Wi-Fi signal strength	View only
12	Setting	Access system settings menu	Click to open
13	Current Design File	View/change active design file	Click/View
14	Elevation Offset	Adjust elevation offset value	Click to modify
15	Horizontal Offset	Adjust horizontal offset value	Click to modify
16	Bucket View	Dynamic bucket visualization	View only
17	Construction Button	Create new construction data	Click to create
18	Real-Time Elevation	Current elevation display	Click/View
19	Electronic bubbles	Shows excavator body angle	View only
20	Construction Mileage	Real-time bucket tip mileage	Click/View
21	Bucket Guide Point	Guide point toggle	Click to switch
22	Bucket List	Access bucket selection	Click to open
23	Bucket Position	Initialize bucket position	Click to set



2. Position Configuration

To access position settings, click [Settings] followed by [Position] to enter the position configuration interface. This section includes positioning information and datalink functions



2.1. Positioning Information

Select [Positioning Information] to view differential and network information.

➔ Return		Position	ing information				
Differential Inform	ation			1	Net Inf	formation	
RTK Mode (main)	Fixed	RTK Mode (aux)	N/A		Teleco	om Operator	>
Latitude (main)	31°46'11.11417"	Latitude (aux)	N/A		Signal	Strength	N/A
Longitude (main)	118°43'36.71906"	Longitude (aux)	N/A		Ping		No network connection
Height (main)	49.37m	Height (aux)	N/A				
SVs Used (main)	44	SVs Used (aux)	N/A				
Delay	0.6s	Heading	20.81°				
Base station Lat	N/A	Pitch	-4.86°				
Base station Lon	N/A	PDOP	0.00				
Base station Height	N/A	VRMS	0.02m				
Base station Distanc	ce N/A	HRMS	0.01m				



2.1.1. Differential Information

The system displays:

- Main and auxiliary antenna solution status
- Latitude and longitude coordinates
- Elevation
- Satellite count
- Differential age
- Base station position
- Heading angle
- Pitch angle
- Key accuracy indicators: PDOP (Position accuracy factor, target: <2)

VRMS (Vertical accuracy factor, target: <0.02)

HRMS (Horizontal accuracy factor, target <0.02)

2.1.2. Network Information

Displays:

- Current network operator
- Signal strength
- Ping value

➡ Return		Position	ing information		
Differential Inform	nation			Net Information	
RTK Mode (main)	Fixed	RTK Mode (aux)	N/A	Telecom Operator	>
Latitude (main)	31°46'11.11417"	Latitude (aux)	N/A	Signal Strength	N/A
Longitude (main)	118°43'36.71906"	Longitude (aux)	N/A	Ping No netwo	rk connection
Height (main)	49.37m	Height (aux)	N/A		
SVs Used (main)	44	SVs Used (aux)	N/A		
Delay	0.6s	Heading	20.81°		
Base station Lat	N/A	Pitch	-4.86°		
Base station Lon	N/A	PDOP	0.00		
Base station Height	N/A	VRMS	0.02m		
Base station Distan	ce N/A	HRMS	0.01m		



2.2. Datalink

Select [Datalink] to configure connection options:

- Quick CORS (VRS)
- Quick CORS (Single Base Station)
- CORS
- APIS
- Radio

➡ Return		Datalink		
QUICK CORS (VRS)	QUICK CORS (SINGLE)	CORS	APIS	RADIO
	Log in to SWAS fail	Error ed! Please check no Reapply	etwork connection!	

2.2.1. Quick CORS

Quick CORS provides automatic connection to CHC SWAS network base stations without manual configuration.

2.2.2. CORS Account Setup

- 1. Select [CORS] > [+ New CORS]
- 2. Enter required information:
 - Account name
 - Server address
 - Port number
 - Source lists



- Username
- Password
- 3. Select [Save] to apply settings

Seturn → Return	CORS account
* Name	Please enter
* Address	Please enter
* Port	Please enter
* Source List	Please enter 🛛 💆
* Username	Please enter
* Password	Please enter 54
	Cancel Save



2.2.3. APIS Account Steup

- 1. Select [APIS] > [+ New APIS]
- 2. Enter required information:
 - Account name
 - Server address
 - Port number
 - Base station SN
- 3. Select [Save] to apply settings

→ Return	New APIS account
*Name	Please enter
* Address	Please enter 🚟
* Port	Please enter
* Base station SN	Please enter
	× Cancel × Save



2.2.4. Radio Configuration

- 1. Select [Radio] > [+ New Radio Account]
- 2. Configure radio parameters:
 - Account name
 - Protocol type
 - Step value
 - Baud rate
 - Channel
 - Frequency
- 3. Select [Save] to apply settings

⊃ Return	New radio base station
* Name	Please enter
* Protocol	Please enter >
* Step value	Please enter >
* Baud Rate	Please enter >
* Channel	Please enter >
* Frequency	Please enter
	X Cancel Save



3. Work Configuration

Access work settings by selecting [Work] from the main menu. This section includes:

- Design file management
- Elevation calibration
- Start station setup
- Vertical offset adjustment
- Horizontal offset adjustment



3.1. Design File

Click [Design File] to enter the design file interface. This screen displays all design files for viewing and modification. Click [More] to create new design files or delete existing files.



★ Return	Design File	More 🗠
		🕂 PLANE
	k	🕒 LINE
	🕐 . 👝 👘 👘	🕀 SLOPE
	- 1	m Delete All
	No Project Files	
	Click More to obtain project files	

3.1.1. New Plane

- 1. Click [PLANE] to enter plane configuration
- 2. Select bucket tip guide points
- 3. Configure elevation collection (Click collect to read value of bucket elevation)
- 4. Enter measure value and cut/fill values as needed

➡ Return	PLANE
Measure	After select the Guidance tip of the Buceket, then placed on the right surface, and Click Measure.
	Selection of Work Point Current Left Tip
	0.00 m CUT/FILL Value 0.00 m + Design Elevation N/A
	Start



3.1.2. New Line

- 1. Click [LINE] to enter line configuration
- 2. Select bucket tip guide points
- 3. Collect elevation points A and B
- 4. Enter cut/fill values
- 5. Click [Next] for slope settings

Note: Points A and B can be placed anywhere along the line. The AB line extends indefinitely in both directions.

➡ Return	LINE
Set Line AB	1/3 Place the bucket at the point AB, click A or B, and then enter CUT/ FILL Value(default 0).
A A A A A A A A A A A A A A A A A A A	Selection of Work Point: Current Left Tip Distance:N/A Distance:N/A Name LINE-20241207-1 CUT/FILL Value 0.00
	C Next



Slope configuration:

- 1. Adjust longitudinal slope values for lines A and B
- 2. Click [Next] to proceed to width settings (if no adjustment needed)
- 3. Enter left and right width values
- 4. Click [Start]to begin line guidance

➡ Return	LINE			
	2	/3		
Adjust main Slope Value	Adjust the main slope value of the line AB, or click Next.			
	Selection of Work Point Current Left Tip			
₽	AB SLOPE			
	- 0.00 % +			
19.96m	AB ERROR			
	— 0 🛞 m 🕂			
	Trevious			
D Return	LINE			
⊃ Return	LINE 3	/3		
Return Input width	LINE 3 Selection of Work Point Current Left Tip	/3		
Return Input width	LINE Selection of Work Point Current Left Tip	/3		
 Return Input width 	LINE 3 Selection of Work Point Current Left Tip Left width (L) 1 m +	1/3		
Return Input width	Selection of Work Point Current Left Tip Left width (L) 1 Right width (R)	3/3		
Return Input width	Selection of Work Point Current Left Tip Left width (L) - 1 m Right width (R) - 1 & m	8/3		
Return Input width	Selection of Work Point Current Left Tip Left width (L) - 1 Right width (R) - 1	3/3		
• Input width	Selection of Work Point Current Left Tip Left width (L) - 1 Right width (R) - 1	3/3		
• Input width	LINE Selection of Work Point Current Left Tip Left width (L) 1 m + Right width (R) 1 & m + Previous M Start	8/3		

Note: A width value of 0 creates an inclined plane design.



3.1.3. New Slope

- 1. Click [SLOPE] for slope configuration
- 2. Select bucket tip guidance points
- 3. Configure:
 - A/B point collection
 - Elevation A settings
 - Elevation difference (B-A)
 - Cut/fill values

➡ Return	SLOPE
	1/2
• Choose Reference Line	Place the bucket tip at Point A&B,then click the Button A&B to measure them
	Selection of Work Point: Current Left Tip
	Distance:N/A B
	Name
Lower Reference Line	SLOPE-20241207-1
	Height A
	N/A m
	Slope A-B
	N/A %
	C* Next



Slope setup:

- 1. Position bucket tip at points A and B
- 2. Click respective buttons to measure coordinates
- 3. Verify A-B longitudinal slope
- 4. Adjust slope value if needed
- 5. Click [Next] for cross slope settings

Seturn	SLOPE	
		2/2
 Select Position of Slope 	С	
B A	Slope Ratio (i)	
	- 1: 1.50	+
A-B Left	Vertical height (h)	
	2.00	m 🕂
A-B Right H	Horizontal distance (L)	
	3.00	m 🕂
	Slope length	
	- 3.60	m 🕂
	The Previous	Start

Final Configuration:

- 1. Position bucket on slope
- 2. Click [C] for automatic slope position and ratio detection
- 3. Verify parameters
- 4. Click [Start] to begin work guidance

3.1.4. Delete Files

Click [Delete] to remove selected design files from the system.



3.2. Elevation Calibration

- 1. Click [Elevation Calibration]
- 2. View real-time point guide elevation
- 3. Compare bucket tip elevation with location elevation
- 4. Calculate correction value:

Correction = Location elevation – Real-time elevation

- 5. Enter correction value
- 6. Click [Save] to apply

⇒ Return Elev	vation calibration
	Current Elevation 48.86 Correction Value 0.00 m + Corrected real-time elevation. 48.86
	Cancel Save



3.3. Start Station

- 1. Click [Start Station]
- 2. View current design data point A pile number
- 3. Verify or modify point A pile number
- 4. Click [Save] to apply changes

⊃ Return	Start Station
	Point A distance of road section Image: Description of the section of the sectio
	× Cancel ✓ Save

Note: This function is available only for line and slope files.



3.4. Vertical Offset

- 1. Click [Vertical Offset]
- 2. Select offset type:
 - Horizontal
 - Orthogonal
- 3. Enter offset value
- 4. Click [Save] to apply

➡ Return	Vertical Offset
	Offset Type Vertical Orthogonal Offset Value 0.0 m +
	Cancel Save



3.5. Horizontal Offset

- 1. Click [Horizontal Offset]
- 2. Enter offset value:
 - Positive: AB line shifts right
 - Negative: AB line shifts left
- 3. Click [Save] to apply





4. System Configuration

Click the [SYSTEM] button to enter the system configuration interface, which includes the general settings and notification settings.



4.1. General Settings

Access general settings through [Settings] > [General]. Configure the following parameters:

Display Settings

- Language selection
- Unit system (Metric/Imperial)
- Screen brightness
- Volume control
- Auto-lock time
- Time zone selection

Seturn Setur	General Settings	
Language		Auto >
Time Zone settings		China Standard Time >
		× Cancel ✓ Save

Guide Settings

- Guide point selection
- Guideline display
- Guide point size
- Guideline width
- Color scheme selection

Tolerance Settings

- 1. Vertical tolerance:
- Green zone: ±3cm
- Yellow zone: ±6cm
- Red zone: Beyond ±6 cm
- 2. Horizontal tolerance:
- Green zone: ±5cm
- Yellow zone: ±10cm
- Red zone: Beyond ±10cm



4.2. Notification Settings

Configure system alerts and notifications:

Sound Alerts

- Enable/disable sound
- Alert volume
- Alert types:
- Position loss
- Datalink interruption
- Low battery
- System errors

Visual Alerts

- Pop-up notifications
- Status bar indicators
- Warning messages

➡ Return	Notification Settings	
Approaching the design value		
Warning range		
- 0.3		m 🕂
Sounder		
Alarm Polysyllable 1		>
	× Cancel	✓ Save



5. Machine Management

Please refer to **"EasyNAV Installation and Calibration guide"** for mechanical configuration.

5.1. Machine Information

View and manage machine details:

- Machine model
- Serial number
- Installation date
- Service history
- Operating hours

5.2. Bucket Management

Add New Bucket

- 1. Click [New Bucket]
- 2. Enter bucket details:
- Name
- Type (Standard/Tilt)
- Dimensions
- 3. Select calibration method
- 4. Follow calibration procedure
- 5. Save configuration



Modify Existing Bucket

- 1. Select bucket from list
- 2. Click [Edit]
- 3. Adjust parameters
- 4. Recalibrate if needed
- 5. Save changes

Delete bucket

- 1. Select bucket
- 2. Click [Delete]
- 3. Confirm deletion

6. About

Click the [ABOUT] button to enter the about configuration interface, which includes the system information, system log, and debug.





6.1. System Information

View system details:

- Software version
- Hardware version
- License information
- Installation date
- Last update
- System status

➔ Return		Syste	em information		
Remote Assistance		System information	n		
If you need help, click the Remote Assistance button below and provide the 6-digit remote identification number to technical support.				Tablet SN ICCID IMEI	unknown
OTA upgrade	OTA upgrade				
To update to the latest system version or board version, click the respective upgrade button below. Do not power off while the upgrade is in progress. Current version: eMG1.0.2.20241204-Simulate-Android Latest version: You are using the most up-to-date version					
				Soard Upgrade	System Upgrade
Name	Model	SN	Version	Status	
Stick Sensor	IS300	19899656	NA/NA	Normal	😴 Upgrade

6.2. System Log

Access system logs for:

- Operation records
- Error messages
- System updates
- Calibration history
- Connection status



Export options:

- 1. Select date range
- 2. Choose log types
- 3. Click [Export]
- 4. Select storage location

S Return	System log	Pack
S GNSS log		
Positioning Heading		
Fault log		
Delayed Accuracy	Sensor	
System		

Note: System logging is turned on by default



7. Appendix

A. Troubleshooting

Common issues and solutions:

Position Loss

- 1. Check GNSS antenna connections
- 2. Verify datalink status
- 3. Check satellite visibility
- 4. Confirm base station connection

Calibration errors

- 1. Verify sensor connections
- 2. Check machine stability
- 3. Ensure proper measurement input
- 4. Repeat calibration process

B. Maintenance

Regular maintenance checklist:

- Check cables and connections regularly
- Verify calibration accuracy occasionally
- Update software when available
- Backup configuration files